MURI Research Update

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Summary of Research from Last year

- 1. Applications of Tests for Independence (with Phyllis and Thomas Mikosch)
- 2. Independent Component Analysis (with Jingjing, John, Sid and Alparsan)
- 3. Random Matrix Theory with Heavy Tails (with Mikosch and students)

Introduction

• Random vectors
$$X \in \mathbb{R}^p$$
 and $Y \in \mathbb{R}^q$,

$$X \perp Y \iff \phi_{X,Y} = \phi_X \phi_Y.$$

where ϕ denotes the characteristic function.

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• Empirical version based on data (time series?) $(X_1, Y_1), \ldots, (X_n, Y_n)$

$$\hat{\mathcal{V}}_n^2(X,Y;w) = \int_{\mathbb{R}^{p+q}} |\hat{\phi}_{X,Y}(t,s) - \hat{\phi}_X(t)\hat{\phi}_Y(s)|^2 w(t,s) dt ds$$

Choice of Weight Function w(s, t)

 For special choices of w(s, t), the empirical distance covariance can be expressed as

$$\frac{1}{n^2} \sum_{k,l} h_1(X_k, X_l) h_2(Y_k, Y_l) + \frac{1}{n^2} \sum_{k,l} h_1(X_k, X_l) \frac{1}{n^2} \sum_{r,s} h_2(Y_r, Y_s) \\ - \frac{2}{n^3} \sum_{k,l,r} h_1(X_k, X_l) h_2(Y_k, Y_r)$$
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$$h_1(x,x') = \phi_5(x-x'), \ h_2(y,y') = \phi_T(y-y').$$

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- No moment constraints
- E.g., symmetric stable $(h_1(x_1, x_2) = \exp\{-c|x_1 x_2|^{\alpha}\})$

Consistency

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• If $\{(X_t, Y_t)\}$ is α -mixing, and $\{X_t\} \perp \{Y_t\}$, then

$$n\hat{\mathcal{V}}_n^2(X,Y) \stackrel{d}{\rightarrow} \int |Q_{X,Y}(s,t)|^2 w(s,t) ds dt,$$

where Q is a zero mean Gaussian process. Could take $Y_t = X_{t+h}$ to get auto-distance covariance for $\{X_t\}$.

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► For independence testing, we can use stationary bootstrap to approximate the distribution of the limit.

Series x









auto distance correlation - Cauchy(0.02)



Multivariate Regular Variation

- ► Set-up: $X_1, X_2, ...$ iid $RV(\alpha)$, $R_i = ||X_i||$, $\Theta = X_i / ||X_i||$.
- Recall: X_i is RV if and only if

$$P(R_i > x) = L(x)x^{-\alpha},$$

with L(x) slowly varying, and:

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Likelihood Estimation

▶ Example: Suppose $P_{\eta}(\Theta \in \cdot)$ has pdf $f(\theta|\eta)$. Estimate MLE from

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► Choice of Threshold: r (large?) s.t. (Θ_i1_[Ri>r], R_i1_[Ri>r]) are approximately independent.

Strategy

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- Use distance correlation to approximate independence of Θ_i and R_i when R_i is large.
- For each r, test the independence of (⊖1_[R>r], R1_[R>r]) from the data until the result becomes significant.

A simulated example (cont.)

Here *R* is independent of Θ iff $R > r_{0.9}$.



Figure: Simulated data at independence level 0.1.

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P-value path: Given each truncation level, find the p-value of independence test between $\log R_i$'s and Θ_i 's after truncation.



Figure: P-value of test of independence of R and Θ vs. truncation level for simulated data at independence level 0.1.

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Figure: P-value of test of independence of R and Θ vs. truncation level for simulated data at independence level 0.1.

A simulated example (cont.)

Take an independent subsample of size 600 and plot its p-value path.



Figure: P-value of test of independence of R and Θ vs. truncation level for simulated data at independence level 0.1.

A simulated example (cont.) Take another independent subsample and plot its p-value path.



Figure: P-value of test of independence of R and Θ vs. truncation level for simulated data at independence level 0.1.

A simulated example (cont.)

Take another independent subsample and plot its p-value path.



Figure: P-value of test of independence of R and Θ vs. truncation level for simulated data at independence level 0.1.

A simulated example (cont.)

Take 60 independent subsamples and plot their p-value paths.



A simulated example (cont.)

Plot the mean p-value path.



A simulated example (cont.)

If independent, the mean p-value should to center around 0.5.



A simulated example (cont.)

Fit a piece-wise linear spline. See also Sen & Sen (2014).



To do:

- Optimal choice of weight function w(s, t).
- Automatic threshold selection for multivariate heavy-tailed data (perhaps an R package?).
- Other ways to select thresholds: e.g., based on Kolmogorov-Smirnov test (Clauset et al., 2009).

2. ICA (joint with Jingjing, Nolan, Resnick, Alparslan)

The model

$$X_{d\times 1} = A_{d\times d} \cdot S_{d\times 1}$$

• Response
$$X = (x_1, \cdots, x_d)^T$$

- Independent components $S = (S_1, \cdots, S_d)^T$
- Full rank $d \times d$ transformation matrix A
- The goal is to recover the unmixing matrix $W = A^{-1}$ and $S = W \cdot X$

A Strategy: Maximum Likelihood Estimator with Log-Concave Densities

Find

$$f = |\det \hat{W}| \prod_{j=1}^{d} f_j(\hat{w}_j^T x)$$

that optimizes the log-likelihood

$$\int_{\mathbb{R}^d} \log(f) dP_n$$

- Use nonparametric density estimates
- Estimate f in space of d-dimensional log-concave densities
- Log-concave: exponential of piece-wise linear densities, normal, Laplace
- ▶ Not log-concave: t, stable, Pareto

Estimation Procedure

- Start from an arbitrary initial value of \hat{W}
- ▶ Step 1: Find log-concave density estimation \hat{f}_j of $\hat{w}_j^T X$
- Step 2: With \hat{f}_j , update \hat{W} to maximize the log-likelihood

$$\log |\det \hat{W}| + \frac{1}{n} \sum_{i=1}^{n} \sum_{j=1}^{d} \log \hat{f}_j(\hat{w}_j^T x_i)$$

Iterate steps 1 and 2, until convergence of the log-likelihood

Pre-Whitening

 Assume each component of S has finite variance (can relax, c.f. Chen and Bickel (2005))

• Let
$$\Sigma_X = \operatorname{cov}(X)$$
 and $Z = \Sigma_X^{-1/2} X$

- $S = O \cdot Z$, where $O = W \cdot \Sigma_X^{-1/2}$ is an orthogonal matrix
- Number of unknown parameters reduced from d^2 to d(d-1)/2
- In practice, estimate Σ_X with sample covariance matrix $\hat{\Sigma}_X$

Consistency of the Maximum Likelihood Estimator

• If $\int \|x\| dP < \infty$, $\hat{W} \xrightarrow{\text{a.s.}} W$ (Samworth and Yuan (2012))

• If
$$\int \|x\| dP = \infty$$
, $\int_{\mathbb{R}^d} \log(f) dP = -\infty$ for all $f \in \mathcal{F}_d$

- If $\Gamma_S^{-1}\hat{\Sigma}_S^{1/2} \xrightarrow{P} I$, consistency holds for pre-whitened estimator (Chen and Bickel (2005))
 - Γ_S : sample variance matrix of S
 - $\hat{\Sigma}_{S}$: sample covariance matrix of *S*
 - Condition holds for all non-degenerate independent distributions

 $S_1 \sim t_3$, $S_2 \sim t_4$



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M-estimator Based on Nonparametric Mutual Information

- ► Aim to relax the moment condition ∫ ||x||dP < ∞ for heavy-tailed distributions</p>
- For fixed a > 0, find \hat{W} that minimizes

$$\int_{\mathbb{R}^d} \hat{f} dP_n^{\hat{W},\mathsf{a}} - \int_{\mathbb{R}^d} \tilde{f} dP_n^{\hat{W},\mathsf{a}}$$

- \hat{f} : log-concave estimation of $\hat{W}X \cdot \mathbb{1}_{\{\hat{W}X \in [-a,a]^d\}}$
- ▶ \tilde{f} : log-concave estimation of the marginals of $\hat{W}X \cdot \mathbb{1}_{\{\hat{W}X \in [-a,a]^d\}}$

Overcomplete ICA

$$X_{d\times 1} = \underset{d\times m}{A} \cdot \underset{m\times 1}{S}$$

▶ d < m

- Challenge: A not invertible
- For fixed A, infinitely many S such that X = AS because of m − d missing components
- Strategy: for fixed A and f, estimate missing S with maximum likelihood estimators

Estimation Procedure Overcomplete ICA

- Start from an arbitrary initial value of \hat{A} and S such that $X = \hat{A}S$
- Step 1: Find log-concave estimation \hat{f}_j of the distribution of S_j
- Step 2: With \hat{f}_j , update \hat{A} to maximize the log-likelihood
 - With an extra optimization step to estimate missing S
- Iterate steps 1 and 2, until convergence of the log-likelihood

Plans for next year

- Complete project on testing independence in a time series setting.
- Complete project on selection of threshold for multivariate RV data and its offshoots. (Partly joint with Cornell group.)
- Expand development of statistical tools for multivariate heavy tails: parameter estimation of parameters in the spectral distribution with emphasis on network models; changepoints in heavy-tails, etc. (Joint with Cornell team.)
- Complete theory and develop algorithms for the ICA model in the undercomplete case.
- Develop methodology to handle the overcomplete case in ICA (with Nolan)
- Expand the random matrix work (with p and n going to infinity) to the case of nonlinear models. Rank transforms of the rows may be of particular interest.