MURI Update 5.12

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Part I – Inference of preferential attachment model

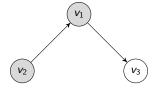
▶ Add one edge each time t



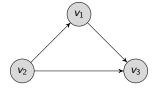
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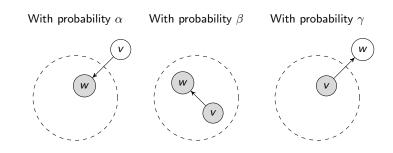


► Add one edge each time t



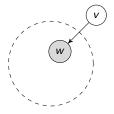
Linear preferential attachment model ($\alpha, \beta, \gamma, \delta_{\rm in}, \delta_{\rm out}$)

► How to add an edge?



Linear preferential attachment model $(\alpha, \beta, \gamma, \delta_{in}, \delta_{out})$

With probability α

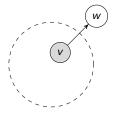


$$Pr(\mathsf{node}\ w\ \mathsf{is}\ \mathsf{chosen}) \propto D_\mathsf{in}(w) + \delta_\mathsf{in}$$

- lacktriangle Small $\delta_{\rm in}$ popular nodes get more attention
- ▶ Very large δ_{in} all node get (almost) equal attention

Linear preferential attachment model $(\alpha, \beta, \gamma, \delta_{in}, \delta_{out})$

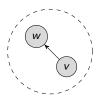
With probability γ



 $Pr(\mathsf{node}\ v\ \mathsf{is}\ \mathsf{chosen}) \propto D_\mathsf{out}(v) + \delta_\mathsf{out}$

Linear preferential attachment model ($\alpha,\beta,\gamma,\delta_{\rm in},\delta_{\rm out})$

With probability β



 $\mathsf{Pr}(\mathsf{nodes}\ w, v\ \mathsf{are}\ \mathsf{chosen}) \propto (D_\mathsf{in}(w) + \delta_\mathsf{in})(D_\mathsf{out}(v) + \delta_\mathsf{out})$

Power laws in degree distributions

• As $n \to \infty$,

$$\frac{N_i^{\text{in}}(n)}{N(n)} \stackrel{\text{a.s.}}{\to} p_i^{\text{in}} \sim i^{-a_1}$$

$$\frac{N^{\text{out}}j(n)}{N(n)} \stackrel{\text{a.s.}}{\to} p_j^{\text{out}} \sim j^{-a_2}$$

with

$$\label{eq:a1} \textit{a}_1 = 1 + \frac{1 + \delta_{\text{in}}(\alpha + \gamma)}{\alpha + \beta}, \quad \textit{a}_2 = 1 + \frac{1 + \delta_{\text{out}}(\alpha + \gamma)}{\beta + \gamma}.$$

Inference on the parameters $(\alpha, \beta, \gamma, \delta_{in}, \delta_{out})$?

The kind of data likely to be available...

- ▶ The full history of the network
- ► A snapshot of the network

MLE estimation for parameters $(\alpha, \beta, \delta_{in}, \delta_{out})$

▶ If the full history of the network with *n* edges is observed

$$\begin{split} L(\alpha,\beta,\delta_{\text{in}},\delta_{\text{out}}) \\ &= \prod_{t=1}^{n} \left(\alpha \frac{D_{\text{in}}^{(t-1)}(v_{t}^{(2)}) + \delta_{\text{in}}}{t-1+\delta_{\text{in}}N(t-1)} \right)^{\mathbf{1}_{\{J_{t}=1\}}} \\ &\times \prod_{t=1}^{n} \left(\beta \frac{D_{\text{in}}^{(t-1)}(v_{t}^{(2)}) + \delta_{\text{in}}}{t-1+\delta_{\text{in}}N(t-1)} \frac{D_{\text{out}}^{(t-1)}(v_{t}^{(1)}) + \delta_{\text{out}}}{t-1+\delta_{\text{out}}N(t-1)} \right)^{\mathbf{1}_{\{J_{t}=2\}}} \\ &\times \prod_{t=1}^{n} \left((1-\alpha-\beta) \frac{D_{\text{out}}^{(t-1)}(v_{t}^{(1)}) + \delta_{\text{out}}}{t-1+\delta_{\text{out}}N(t-1)} \right)^{\mathbf{1}_{\{J_{t}=3\}}} \end{split}$$

Theorem

The MLE estimator

$$\hat{\boldsymbol{\theta}} := (\hat{\alpha}, \hat{\beta}, \hat{\delta}_{\mathsf{in}}, \hat{\delta}_{\mathsf{out}}) = \arg\max L(\alpha, \beta, \delta_{\mathsf{in}}, \delta_{\mathsf{out}})$$

is unique, strongly consistent, and asymptotically normal, i.e.

$$\hat{\boldsymbol{\theta}} \stackrel{\text{a.s.}}{\rightarrow} (\alpha, \beta, \delta_{\text{in}}, \delta_{\text{out}}) =: \boldsymbol{\theta},$$

and

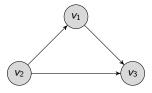
$$\sqrt{n}(\hat{\boldsymbol{\theta}}-\boldsymbol{\theta})\stackrel{d}{\rightarrow} N(\mathbf{0},I^{-1}(\boldsymbol{\theta})),$$

where $I(\theta)$ is the asymptotic Fisher information matrix for the parameters.

One-snapshot estimation for parameters $(\alpha,\beta,\delta_{\rm in},\delta_{\rm out})$

▶ If only a snapshot of the network with n edges is observed,

$$G(n)=\left(V(n),E(n)\right)$$



One-snapshot estimation for parameters $(\alpha, \beta, \delta_{\rm in}, \delta_{\rm out})$

approximate the score functions using law of large numbers

$$\begin{split} &\frac{1}{n}\frac{\partial \log L}{\partial \delta_{\text{in}}} \approx \sum_{i=0}^{\infty} \frac{N_{>i}^{\text{in}}(n)/n}{i+\delta_{\text{in}}} - \frac{1-\alpha-\beta}{\delta_{\text{in}}} - \frac{1-\beta}{1+\delta_{\text{in}}(1-\beta)}(\alpha+\beta) = 0, \\ &\frac{1}{n}\frac{\partial \log L}{\partial \delta_{\text{out}}} \approx \sum_{j=0}^{\infty} \frac{N_{>j}^{\text{out}}(n)/n}{j+\delta_{\text{out}}} - \frac{\alpha}{\delta_{\text{out}}} - \frac{1-\beta}{1+\delta_{\text{in}}(1-\beta)}(1-\alpha) = 0. \end{split}$$

One-snapshot estimation for parameters $(\alpha, \beta, \delta_{\text{in}}, \delta_{\text{out}})$

approximate the score functions using law of large numbers

$$\begin{split} &\frac{1}{n}\frac{\partial \log L}{\partial \delta_{\text{in}}} \approx \sum_{i=0}^{\infty} \frac{N_{>i}^{\text{in}}_{i}(n)/n}{i+\delta_{\text{in}}} - \frac{1-\alpha-\beta}{\delta_{\text{in}}} - \frac{1-\beta}{1+\delta_{\text{in}}(1-\beta)}(\alpha+\beta) = 0, \\ &\frac{1}{n}\frac{\partial \log L}{\partial \delta_{\text{out}}} \approx \sum_{j=0}^{\infty} \frac{N_{>j}^{\text{out}}(n)/n}{j+\delta_{\text{out}}} - \frac{\alpha}{\delta_{\text{out}}} - \frac{1-\beta}{1+\delta_{\text{in}}(1-\beta)}(1-\alpha) = 0. \end{split}$$

moment matching

$$egin{aligned} rac{\mathcal{N}_0^{\mathsf{in}}(n)}{n} &
ightarrow
ho_0^{\mathsf{in}} = rac{lpha}{(1 + rac{lpha + eta}{1 + \delta_{\mathsf{in}}(1 - eta)} \delta_{\mathsf{in}})}, \ rac{\mathcal{N}_0^{\mathsf{out}}(n)}{n} &
ightarrow
ho_0^{\mathsf{in}} = rac{1 - lpha - eta}{(1 + rac{1 - lpha}{1 + \delta_{\mathsf{out}}(1 - eta)} \delta_{\mathsf{out}})}. \end{aligned}$$

▶ Solve the above equations to obtain $\tilde{\theta} = (\tilde{\alpha}, \tilde{\beta}, \tilde{\delta}_{\text{in}}, \tilde{\delta}_{\text{out}})$

Theorem: strong consistency of the one-snapshot estimation

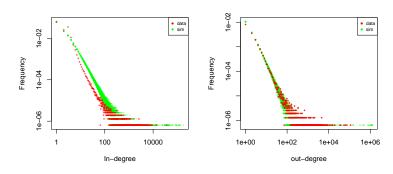
The estimator $\tilde{\boldsymbol{\theta}} := (\tilde{\alpha}, \tilde{\beta}, \tilde{\delta}_{\text{in}}, \tilde{\delta}_{\text{out}})$ is unique and strongly consistent, i.e.

$$ilde{m{ heta}} \stackrel{ ext{a.s.}}{ o} m{ heta}.$$

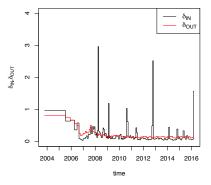
- Asymptotic normality is implied from simulations but yet to be proved (Tiandong?)
- From the simulations, $\tilde{\theta}$ can achieve \sim 20% efficiency compared to MLE, since less information is provided.

- $\,\blacktriangleright\,$ $A \to B:$ user A writing a message on the talk page of user B
- ▶ 225,749 nodes (users) and 1,554,699 edges (messages)
- ▶ full history available

► Goodness-of-fit of degree distributions

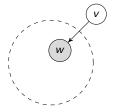


- lacktriangle Separate the network into \sim 150 time intervals
- ▶ Fit the model in each interval



Linear preferential attachment model $(\alpha, \beta, \gamma, \delta_{in}, \delta_{out})$

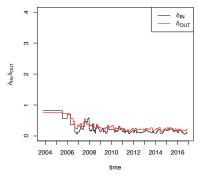
With probability α



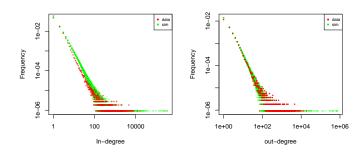
$$Pr(\mathsf{node}\ w\ \mathsf{is}\ \mathsf{chosen}) \propto D_\mathsf{in}(w) + \delta_\mathsf{in}$$

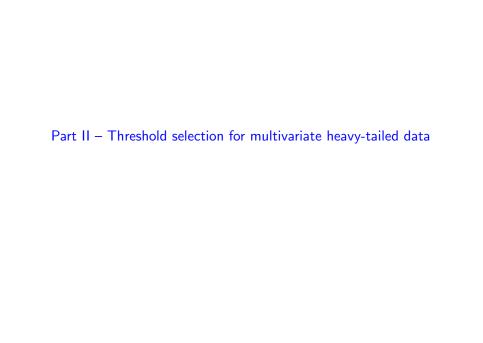
- lacktriangle Small $\delta_{\rm in}$ popular nodes get more attention
- ▶ Very large δ_{in} all node get (almost) equal attention

- ▶ Discover the existence of accounts with broadcasting feature
- ▶ Remove 37 administrative accounts



▶ Re-fit the linear preferential attachment model





Multivariate regular variation

Let
$$(R, \Theta) = (\|\mathbf{X}\|, \frac{\mathbf{X}}{\|\mathbf{X}\|})$$
, $\mathbf{X} \sim \mathbf{RV}(\alpha)$ if and only if $R \sim RV(\alpha)$ and

$$P(\mathbf{\Theta} \in \cdot | R > r) \to S(\cdot), \quad r \to \infty.$$

Given $(R_1, \Theta_1), \ldots, (R_n, \Theta_n)$, how to model $S(\cdot)$?

▶ Take $\{\Theta_i\}$ for r_0 large

How to choose r_0 ?

▶ Choose r_0 s.t. when conditional on $R > r_0$, Θ and R are approximately independent

How to measure the dependence between Θ and R?

► Distance covariance

A simulated example

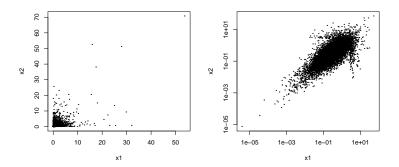


Figure: Simulated ${\bf X}$ where R is independent of Θ only when conditioning on $R>r_{0.9}$.

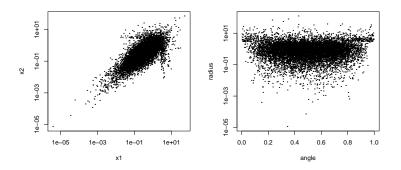


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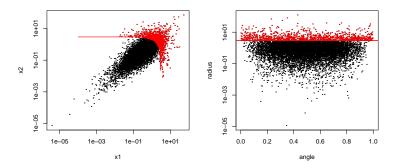


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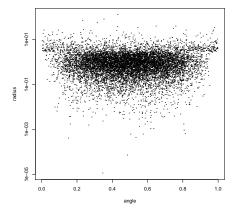


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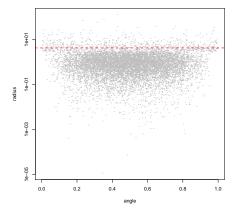


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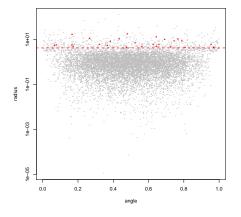


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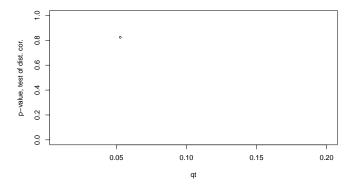


Figure: P-value of test of independence of truncated R and Θ vs. the truncation level. The true independence level is 0.1.

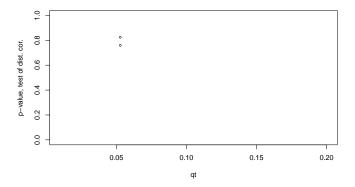


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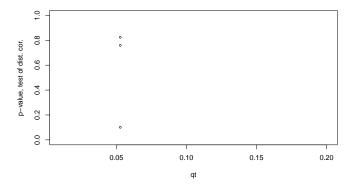


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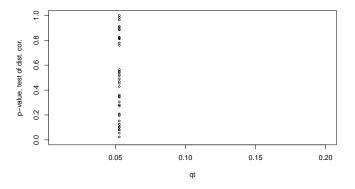


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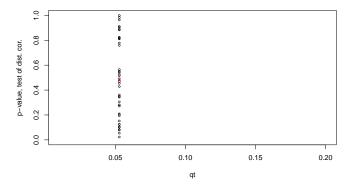


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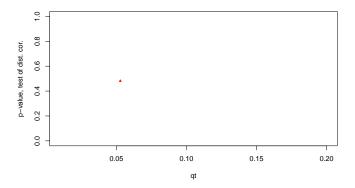


Figure: Mean p-value of test of independence of truncated R and Θ vs. the truncation level. The true independence level is 0.1.

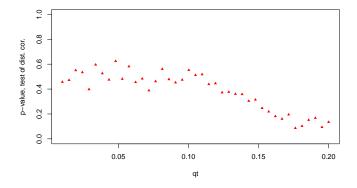


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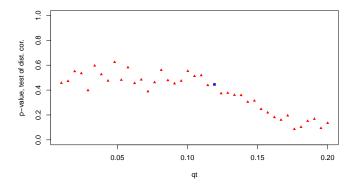


Figure: Mean p-value of test of independence of truncated R and Θ vs. the truncation level. The true independence level is 0.1.

How to choose the change point?

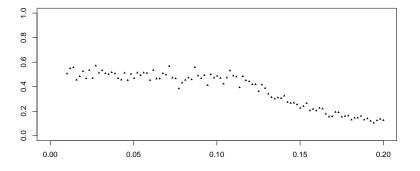


Figure: Mean p-value of test of independence of truncated R and Θ vs. the truncation level. The true independence level is 0.1.

Idea 1: CUSUM algorithm (Page (1954))

For each k,

- ► Consider $\sum_{i=j}^{k} (0.5 pv_i)$ for j = 1, ..., k
- ► Calculate

$$H = \max_{j} \left[\sum_{i=j}^{k} (0.5 - pv_i) \right]$$

▶ Detect change point when *H* exceed a certain threshold *h*₀

Idea 1: CUSUM algorithm

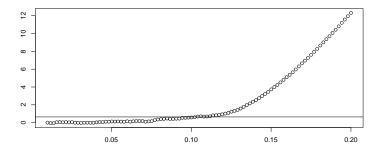


Figure: CUSUM plot for the previous *p*-value path.

Idea 1: CUSUM algorithm

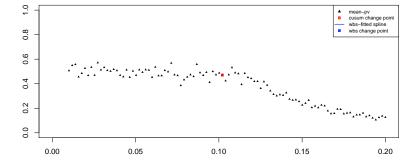


Figure: Mean p-value of test of independence of truncated R and Θ vs. the truncation level. The true independence level is 0.1.

Idea 2: Wild binary segmentation (Fryzlewicz (2014))

- ▶ Based on the CUSUM idea
- ▶ Fit a piecewise constant spline to the data

Idea 2: Wild binary segmentation

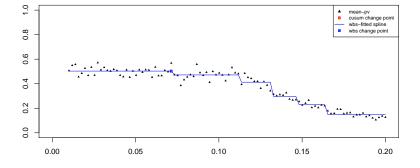


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