

Truncated fractional moments of stable laws

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Abstract

Expressions are given for the truncated fractional moments EX_+^p of a general stable law. These involve families of special functions that arose out of the study of multivariate stable densities and probabilities. As a particular case, an expression is given for $E(X - a)_+$ when $\alpha > 1$.

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1. Introduction

A univariate stable r.v. Z with index α , skewness β , scale γ , and location δ has characteristic function

$$\phi(u) = \phi(u|\alpha, \beta, \gamma, \delta) = E \exp(iuZ) = \exp(-\gamma [|u| + i\beta\eta(u, \alpha)] + iu\delta), \quad (1)$$

where $0 < \alpha \leq 2$, $-1 \leq \beta \leq 1$, $\gamma > 0$, $\delta \in \mathbb{R}$ and

$$\eta(u, \alpha) = \begin{cases} -(\text{sign } u) \tan(\pi\alpha/2)|u| & \alpha \neq 1 \\ (2/\pi) u \ln |u| & \alpha = 1. \end{cases}$$

In the notation of Samorodnitsky and Taqqu (1994), this is a $S(\gamma, \beta, \delta)$ distribution. We will use the notation $X \sim \mathbf{S}(\alpha, \beta, \gamma, \delta; 1)$ (the “1” is used to distinguish between this parameterization and a continuous one used below).

The purpose of this paper is to derive expressions for truncated fractional moments $EX_+^p = E(X \mathbb{1}_{\{X \geq 0\}})^p$ for general stable laws. To do this, define the functions for real x and d

$$g_d(x|\alpha, \beta) = \begin{cases} \int_0^\infty \cos(xr + \beta\eta(r, \alpha)) r^{d-1} e^{-r} dr & 0 < d < \infty \\ \int_0^\infty [\cos(xr + \beta\eta(r, \alpha)) - 1] r^{d-1} e^{-r} dr & -2 \min(1, \alpha) < d \leq 0 \end{cases}$$

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$$\tilde{g}_d(x|\alpha, \beta) = \begin{cases} \int_0^\infty \sin(xr + \beta\eta(r, \alpha)) r^{d-1} e^{-r} dr & -\min(1, \alpha) < d < \infty \\ \int_0^\infty [\sin(xr + \beta\eta(r, \alpha)) - xr] r^{d-1} e^{-r} dr & \alpha > 1, -\alpha < d \leq -1. \end{cases}$$

The functions $g_d(\cdot|\alpha, \beta)$ and $\tilde{g}_d(\cdot|\alpha, \beta)$, for integer subscripts $d = 1, 2, 3, \dots$ were introduced in Abdul-Hamid and Nolan (1998). (The notation was slightly different there: a factor of $(2\pi)^{-d}$ was included in the definition and $g_{\cdot,d}(x, \beta)$ was used instead of $g_d(x|\alpha, \beta)$, while $q_{\cdot,1}(x, \beta)$ was used instead of $\tilde{g}_1(x|\alpha, \beta)$.)

The expressions for EX_+^p will involve the functions $g_{-p}(\cdot|\alpha, \beta)$ and $\tilde{g}_{-p}(\cdot|\alpha, \beta)$, i.e. negative values fractional values of the subscript d . Before proving that result, we show that the functions $g_d(\cdot|\alpha, \beta)$ and $\tilde{g}_d(\cdot|\alpha, \beta)$ have multiple uses. For a standardized univariate stable law, Fourier inversion of the characteristic function shows that the d.f. and density are given by

$$\begin{aligned} F(x|\alpha, \beta) - F(0|\alpha, \beta) &= \frac{1}{\pi} (\tilde{g}_0(x|\alpha, \beta) - \tilde{g}_0(0|\alpha, \beta)) \\ f(x|\alpha, \beta) &= \frac{1}{\pi} g_1(x|\alpha, \beta). \end{aligned} \quad (2)$$

We note that there are explicit formulas for $F(0|\alpha, \beta)$ when $\alpha \neq 1$.

The $g_d(\cdot|\alpha, \beta)$ functions are used in a similar way to give d -dimensional stable densities, see Theorem 1 of Abdul-Hamid and Nolan (1998) (note that there is a sign mistake in that formula when $\alpha = 1$), and Nolan (2017) uses both $g_d(\cdot|\alpha, \beta)$ and $\tilde{g}_d(\cdot|\alpha, \beta)$ to give an expression for multivariate stable probabilities.

Another use of these functions is in conditional expectation of X_2 given $X_1 = x$ when (X_1, X_2) are jointly stable with zero shift and spectral measure Λ . In general, the conditional expectation is a complicated non-linear function; here it is restated in terms of these functions. If $\alpha > 1$ or ($\alpha \leq 1$ and (5.2.4) in Samorodnitsky and Taqqu (1994) holds), then Theorems 5.2.2 and 5.2.3 in Samorodnitsky and Taqqu (1994) show that the conditional expectation exists for x in the support of X_1 and is given by

$$E(X_2|X_1 = x) = \begin{cases} c_1 x + c_2 \left[\frac{1 - (x/\gamma_1) \tilde{g}_1(x/\gamma_1|\alpha, \beta_1)}{g_1(x/\gamma_1|\alpha, \beta_1)/\gamma_1} \right] & \alpha \neq 1 \\ c_0 + c_1 \frac{x - \mu_1}{\gamma_1} + c_2 \frac{\tilde{g}_1((x - \mu_1)/\gamma_1 - (2\beta_1/\pi) \ln \gamma_1|1, \beta_1)}{g_1(x/\gamma_1|1, \beta_1)} & \alpha = 1, \beta_1 \neq 0 \\ c_0 + c_1 \frac{x - \mu_1}{\gamma_1} + c_2 \left[\frac{\gamma_1 [(1 - \ln \gamma_1) g_1((x - \mu_1)/\gamma_1|1, 0) + h_1((x - \mu_1)/\gamma_1|1, 0)]}{g_1(x/\gamma_1|1, 0)} \right] & \alpha = 1, \beta_1 = 0, \end{cases}$$

where β_1 and γ_1 are the skewness and scale parameters of X_1 , and the constants and function $h_1(\cdot|1, 0)$ are given by

$$c_0 = -\frac{2}{\pi} \int_{\mathcal{S}} s_2 \ln |s_1| \Lambda(ds)$$

$$\begin{aligned}
c_1 &= \begin{cases} \frac{\kappa_1 + \beta_1 \tan^2(\pi\alpha/2)\kappa_2}{\gamma_1(1 + \beta_1^2 \tan^2(\pi\alpha/2))} & \alpha \neq 1 \\ \kappa_2/\beta_1 & \alpha = 1, \beta_1 \neq 0 \\ \kappa_1 & \alpha = 1, \beta_1 = 0 \end{cases} \\
c_2 &= \begin{cases} \frac{\tan(\pi\alpha/2)(\kappa_2 - \beta_1\kappa_1)}{\gamma_1(1 + \beta_1^2 \tan^2(\pi\alpha/2))} & \alpha \neq 1 \\ (\kappa_2 - \beta_1\kappa_1)/\beta_1 & \alpha = 1, \beta_1 \neq 0 \\ -2\kappa_2/\pi & \alpha = 1, \beta_1 = 0 \end{cases} \\
\kappa_1 &= [X_2, X_1] = \begin{cases} \int_{\mathbb{S}} s_2 s_1^{\langle -1 \rangle} \Lambda(ds) & \alpha \neq 1 \\ \int_{\mathbb{S}} s_2 s_1^{\langle 0 \rangle} \Lambda(ds) = \int_{\mathbb{S}} s_2 \operatorname{sign}(s_1) \Lambda(ds) & \alpha = 1 \end{cases} \\
\kappa_2 &= \int_{\mathbb{S}} s_2 |s_1|^{-1} \Lambda(ds) \\
\mu_1 &= -\frac{2}{\pi} \int_{\mathbb{S}} s_1 \ln |s_1| \Lambda(ds) \\
h(x|1, 0) &= \int_0^\infty \cos(xr)(\log r)e^{-r} dr.
\end{aligned}$$

In the terms above, \mathbb{S} is the unit circle and $[X_2, X_1]$ is the α -covariation. Note that if Λ is symmetric, then $c_0 = \kappa_2 = \beta_1 = \mu_1 = 0$, so $c_2 = 0$ and

$$E(X_2|X_1 = x) = \frac{[X_2, X_1]}{\gamma_1} x$$

is linear.

2. Truncated moments EX_+^p

The main result of this paper is the following expression for the fractional truncated moment of a stable r.v.

Theorem 1. *Let $X \sim \mathbf{S}(\alpha, \beta, \gamma, \delta; 1)$ with any $0 < \alpha < 2$ and any $-1 \leq \beta \leq 1$ and set*

$$\delta^* = \begin{cases} \delta/\gamma & \alpha \neq 1 \\ \delta/\gamma + (2/\pi)\beta \log \gamma & \alpha = 1. \end{cases}$$

For $p < \alpha$, define $m^p(\alpha, \beta, \gamma, \delta) = EX_+^p$.

(a) When $p = 0$,

$$m^0(\alpha, \beta, \gamma, \delta) = P(X > 0) = \frac{1}{2} - \frac{1}{\pi} \tilde{g}_0(-\delta^*|\alpha, \beta).$$

When $0 < p < \min(1, \alpha)$,

$$\begin{aligned}
m^p(\alpha, \beta, \gamma, \delta) &= \gamma^p \frac{\Gamma(p+1)}{\pi} \left[\sin\left(\frac{\pi p}{2}\right) \left(\frac{\Gamma(1-p/\alpha)}{p} - g_{-p}(-\delta^*|\alpha, \beta) \right) \right. \\
&\quad \left. - \cos\left(\frac{\pi p}{2}\right) \tilde{g}_{-p}(-\delta^*|\alpha, \beta) \right].
\end{aligned}$$

When $p = 1 < \alpha < 2$,

$$m^p(\alpha, \beta, \gamma, \delta) = \gamma \left[\frac{\delta^*}{2} + \frac{1}{\pi} (\Gamma(1 - 1/\alpha) - g_{-1}(-\delta^*|\alpha, \beta)) \right].$$

When $1 < p < \alpha < 2$,

$$m^p(\alpha, \beta, \gamma, \delta) = \gamma^p \frac{\Gamma(p+1)}{\pi} \left[\sin\left(\frac{\pi p}{2}\right) \left(\frac{\Gamma(1-p/\alpha)}{p} - g_{-p}(-\delta^*|\alpha, \beta) \right) + \cos\left(\frac{\pi p}{2}\right) \left(\frac{\delta^*}{\alpha} \Gamma((1-p)/\alpha) - \tilde{g}_{-p}(-\delta^*|\alpha, \beta) \right) \right].$$

$$(b) EX_-^p = E(-X)_+^p = m^p(\alpha, -\beta, \gamma, -\delta).$$

Proof (a) To simplify calculations, first assume $\gamma = 1$; the adjustment for $\gamma \neq 1$ is discussed below. When $p = 0$, $EX_+^0 = \int_0^\infty 1 f(x) dx = P(X > 0)$, and (2) and $\tilde{g}_0(x|\alpha, \beta) \rightarrow \pi/2$ as $x \rightarrow \infty$ gives the value in terms of $\tilde{g}_0(\cdot|\alpha, \beta)$. When $0 < p < \min(1, \alpha)$, Corollary 2 of Pinelis (2011) with $k = \ell = 0$ shows

$$EX_+^p = \frac{\Gamma(p+1)}{\pi} \int_0^\infty \Re \frac{\phi(u) - 1}{(iu)^{p+1}} du. \quad (3)$$

First assume $\alpha \neq 1$ and set $\zeta = \zeta(\alpha, \beta) = -\beta \tan \frac{\pi}{2}$ and restricting to $u > 0$,

$$\begin{aligned} \frac{\phi(u) - 1}{(iu)^{p+1}} &= \left(\left[e^{-u(1+i\zeta)+i\delta u} - 1 \right] (-i)e^{-i(\pi/2)p} \right) u^{-p-1} \\ &= \left(-i \left(e^{-u} [\cos(\delta u - \zeta u) + i \sin(\delta u - \zeta u)] - 1 \right) e^{-i(\pi/2)p} \right) u^{-p-1} \\ &= \left(\left[e^{-u} \sin(\delta u - \zeta u) - i \left(e^{-u} \cos(\delta u - \zeta u) - 1 \right) \right] [\cos(\frac{\pi p}{2}) - i \sin(\frac{\pi p}{2})] \right) u^{-p-1} \end{aligned}$$

And therefore

$$\begin{aligned} \Re \frac{\phi(u) - 1}{(iu)^{p+1}} &= \left[\cos\left(\frac{\pi p}{2}\right) e^{-u} \sin(\delta u - \zeta u) - \sin\left(\frac{\pi p}{2}\right) \left(e^{-u} \cos(\delta u - \zeta u) - 1 \right) \right] u^{-p-1} \\ &= \cos\left(\frac{\pi p}{2}\right) \sin(\delta u - \zeta u) u^{-p-1} e^{-u} \\ &\quad - \sin\left(\frac{\pi p}{2}\right) \left([\cos(\delta u - \zeta u) - 1] u^{-p-1} e^{-u} + (e^{-u} - 1) u^{-p-1} \right) \end{aligned}$$

Integrating this from 0 to ∞ , substituting $t = u$ in the last term to get

$$EX_+^p = \frac{\Gamma(p+1)}{\pi} [-\cos\left(\frac{\pi p}{2}\right) \tilde{g}_{-p}(-\delta|\alpha, \beta) - \sin\left(\frac{\pi p}{2}\right) \{g_{-p}(-\delta|\alpha, \beta) - \Gamma(1-p/\alpha)/p\}].$$

Next consider $0 < p < \alpha = 1$. Use (3) again, so we need to simplify

$$\frac{\phi(u) - 1}{(iu)^{p+1}} = \left(\left[e^{-u(1+i\eta(u,1))+i\delta u} - 1 \right] (-i)e^{-i(\pi/2)p} \right) u^{-p-1}$$

$$\begin{aligned}
&= \left(-i \left(e^{-u} [\cos(\delta u - \beta\eta(u, 1)) + i \sin(\delta u - \beta\eta(u, 1))] - 1 \right) e^{-i(\pi/2)p} \right) u^{-p-1} \\
&= \left([e^{-u} \sin(\delta u - \beta\eta(u, 1)) - i (e^{-u} \cos(\delta u - \beta\eta(u, 1)) - 1)] \right. \\
&\quad \left. \times [\cos(\frac{\pi p}{2}) - i \sin(\frac{\pi p}{2})] \right) u^{-p-1} \\
\Re \frac{\phi(u) - 1}{(iu)^{p+1}} &= \left[\cos(\frac{\pi p}{2}) e^{-u} \sin(\delta u - \beta\eta(u, 1)) \right. \\
&\quad \left. - \sin(\frac{\pi p}{2}) (e^{-u} (\cos(\delta u - \beta\eta(u, 1)) - 1) + (e^u - 1)) \right] u^{-p-1}.
\end{aligned}$$

Integrating from 0 to ∞ yields

$$EX_+^p = \frac{\Gamma(p+1)}{\pi} [-\cos(\frac{\pi p}{2}) \tilde{g}_{-p}(-\delta|1, \beta) - \sin(\frac{\pi p}{2}) \{g_{-p}(-\delta|1, \beta) - \Gamma(1-p)/p\}].$$

When $p = 1 < \alpha < 2$, EX exists and is equal to δ . Using Corollary 2 of Pinelis (2011) with $k = 1$, $\ell = 0$ shows

$$EX_+ = \frac{1}{2}EX + \frac{\Gamma(2)}{\pi} \int_0^\infty \Re \frac{\phi(u) - 1}{(iu)^{p+1}} du = \frac{\delta}{2} + \frac{1}{\pi} \int_0^\infty \Re \frac{\phi(u) - 1}{(iu)^{p+1}} du.$$

The integrand is the same as above, with $\cos(\frac{\pi p}{2}) = 0$ and $\sin(\frac{\pi p}{2}) = 1$, so

$$EX_+ = \frac{\delta}{2} - \frac{1}{\pi} [g_{-1}(-\delta|\alpha, \beta) - \Gamma(1-1/\alpha)].$$

When $1 < p < \alpha < 2$, Corollary 2 of Pinelis (2011) with $k = \ell = 1$ shows

$$EX_+^p = \frac{\Gamma(p+1)}{\pi} \int_0^\infty \Re \frac{\phi(u) - 1 - iuEX}{(iu)^{p+1}} du, \quad (4)$$

Since $\alpha > 1$, EX exists and is equal to δ . As above, for $u > 0$,

$$\begin{aligned}
\frac{\phi(u) - 1 - iu\delta}{(iu)^{p+1}} &= \left([e^{-u(1+i\zeta u)} + i\delta u - 1 - i\delta u] (-i)e^{-i(\pi/2)p} \right) u^{-p-1} \\
&= \left(-i \left(e^{-u} [\cos(\delta u - \zeta u) + i \sin(\delta u - \zeta u)] - 1 - i\delta u \right) e^{-i(\pi/2)p} \right) u^{-p-1} \\
&= \left[\left(e^{-u} \sin(\delta u - \zeta u) - \delta u \right) - i \left(e^{-u} \cos(\delta u - \zeta u) - 1 \right) \right] \\
&\quad \times [\cos(\frac{\pi p}{2}) - i \sin(\frac{\pi p}{2})] u^{-p-1}
\end{aligned}$$

And therefore

$$\begin{aligned}
\Re \frac{\phi(u) - 1 - iu\delta}{(iu)^{p+1}} &= \left[\cos(\frac{\pi p}{2}) \left(e^{-u} \sin(\delta u - \zeta u) - \delta u \right) \right. \\
&\quad \left. - \sin(\frac{\pi p}{2}) \left(e^{-u} \cos(\delta u - \zeta u) - 1 \right) \right] u^{-p-1} \\
&= \cos(\frac{\pi p}{2}) \left([\sin(\delta u - \zeta u) - \delta u] u^{-p-1} e^{-u} + \delta (e^{-u} - 1) u^{-p} \right) \\
&\quad - \sin(\frac{\pi p}{2}) \left([\cos(\delta u - \zeta u) - 1] u^{-p-1} e^{-u} + (e^{-u} - 1) u^{-p-1} \right)
\end{aligned}$$

Plugging this into (4) and integrating yields

$$EX_+^p = \frac{\Gamma(p+1)}{\pi} \left\{ \cos\left(\frac{\pi p}{2}\right) [-\tilde{g}_{-p}(-\delta|\alpha, \beta)] + (\delta/\alpha)(\Gamma((1-p)/\alpha)) \right. \\ \left. + \sin\left(\frac{\pi p}{2}\right) [-g_{-p}(-\delta|\alpha, \beta) + \Gamma(1-p/\alpha)/p] \right\}$$

Now consider $\gamma \neq 1$. If $X \sim \mathbf{S}(\alpha, \beta, \gamma, \delta; 1)$, then $X \stackrel{d}{=} \gamma Y$, where $Y \sim \mathbf{S}(\alpha, \beta, 1, \delta^*; 1)$, so $EX_+^p = \gamma^p EY_+^p$. In symbols,

$$m^p(\alpha, \beta, \gamma, \delta) = \gamma^p m^p(\alpha, \beta, 1, \delta^*).$$

(b) This follows from $-X \sim \mathbf{S}(\alpha, -\beta, \gamma, -\delta; 1)$. \square

When $-1 < p < 0$, we conjecture that

$$m^p(\alpha, \beta, \gamma, \delta) = \gamma^p \frac{\Gamma(p+1)}{\pi} [-\sin\left(\frac{\pi p}{2}\right) g_{-p}(-\delta^*|\alpha, \beta) - \cos\left(\frac{\pi p}{2}\right) \tilde{g}_{-p}(-\delta^*|\alpha, \beta)].$$

3. Related results

There are several corollaries to the preceding result. First, taking $p = 1$ in the previous result shows the following.

Corollary 2. *If $X \sim \mathbf{S}(\alpha, \beta, \gamma, \delta; 1)$ with $\alpha > 1$, $-1 \leq \beta \leq 1$, $a \in \mathbb{R}$*

$$E(X-a)_+ = \frac{\delta-a}{2} + \frac{\gamma}{\pi} \left[\Gamma\left(1 - \frac{1}{\alpha}\right) - g_{-1}\left(\frac{\delta-a}{\gamma} \mid \alpha, \beta\right) \right].$$

Combining parts (a) and (b) of Theorem 1 yields.

Corollary 3. *If $X \sim \mathbf{S}(\alpha, \beta, \gamma, \delta; 1)$ with $0 < \alpha < 2$, $-1 \leq \beta \leq 1$, $-1 \leq p < \alpha$.*

$$E|X|^p = \gamma^p \frac{2\Gamma(p+1)}{\pi} \sin\left(\frac{\pi p}{2}\right) \left(\frac{\delta^* \Gamma(1-p/\alpha)}{p} \mathbb{1}_{\{p>0\}} - g_{-p}(-\delta^*|\alpha, \beta) \right) \\ EX^{<p>} = \gamma^p \frac{2\Gamma(p+1)}{\pi} \cos\left(\frac{\pi p}{2}\right) \left(\frac{\delta^* \Gamma((1-p)/\alpha)}{\alpha} \mathbb{1}_{\{p>1\}} - \tilde{g}_{-p}(-\delta^*|\alpha, \beta) \right).$$

Proof $E|X|^p = EX_-^p + EX_+^p = m^p(\alpha, \beta, \gamma, \delta) + m^p(\alpha, -\beta, \gamma, -\delta)$ and $EX^{<p>} = m^p(\alpha, \beta, \gamma, \delta) - m^p(\alpha, -\beta, \gamma, -\delta)$. Use Theorem 1 and the reflection property: $g_d(-x|\alpha, \beta) = g_d(x|\alpha, -\beta)$. Note that as $p \rightarrow 0$, $E|X|^p \rightarrow E1 = 1$ and $EX^{<p>} \rightarrow -(2/\pi) \tilde{g}_0(\delta^*|\alpha, \beta) = P(X > 0) - P(X < 0) = 1 - 2F(0)$. Also as $p \rightarrow 1$, $EX^{<p>} \rightarrow \delta$. \square

In the strictly stable case, the expressions for EX_+^p can be simplified using closed form expressions for $g_d(0|\alpha, \beta)$ and $\tilde{g}_d(0|\alpha, \beta)$ when $\alpha \neq 1$. To state the result, set

$$\theta_0 = \theta_0(\alpha, \beta) = \begin{cases} \alpha^{-1} \arctan(\beta \tan \frac{\pi}{2}) & \alpha \neq 1 \\ \pi/2 & \alpha = 1. \end{cases}$$

Lemma 4. When $\alpha \neq 1$,

$$g_d(0|\alpha, \beta) = \begin{cases} (\cos \alpha \theta_0)^{d/\alpha} \cos(d \theta_0) \Gamma(1 + d/\alpha)/d & d > 0 \\ (\ln(\cos \alpha \theta_0))/\alpha & d = 0 \\ [(\cos \alpha \theta_0)^{d/\alpha} \cos(d \theta_0) - 1] \Gamma(1 + d/\alpha)/d & -\alpha < d < 0 \end{cases}$$

$$\tilde{g}_d(0|\alpha, \beta) = \begin{cases} -(\cos \alpha \theta_0)^{d/\alpha} \sin(d \theta_0) \Gamma(1 + d/\alpha)/d & d \in (-\alpha, 0) \cup (0, \infty) \\ -\theta_0 & d = 0. \end{cases}$$

Proof Substitute $u = r$ in the expressions for $g_d(0|\alpha, \beta)$ and $\tilde{g}_d(0|\alpha, \beta)$. Then use respectively the integrals 3.944.6, 3.948.2, 3.945.1, 3.944.5, and 3.948.1 pg. 492-493 of Gradshteyn and Ryzhik (2000). (Note that some of these formulas have mistyped exponents.) Finally, when $\alpha \neq 1$, $\alpha \theta_0 = -\arctan \zeta$, and for the allowable values of α and θ_0 ,

$$\cos \alpha \theta_0 = |\cos \alpha \theta_0| = (1 + \tan^2 \alpha \theta_0)^{-1/2} = (1 + \zeta^2)^{-1/2}.$$

□

The following is a different proof of Theorem 2.6.3 of Zolotarev (1986).

Corollary 5. Let X be strictly stable, e.g. $X \sim \mathbf{S}(\alpha, \beta, \gamma, 0; 1)$ with $\alpha \neq 1$ or ($\alpha = 1$ and $\beta = 0$) and $0 < p < \alpha$.

(a) The fractional moment of the positive part of X is

$$EX_+^p = \frac{\gamma^p}{(\cos \alpha \theta_0)^{p/\alpha}} \frac{\Gamma(1 - p/\alpha) \sin p(\pi/2 + \theta_0)}{\Gamma(1 - p) \sin(p\pi)}.$$

(b) The fractional moment of the negative part of X is $EX_-^p = E(-X)_+^p$, which can be obtained from the right hand side above by replacing θ_0 with $-\theta_0$.

When $p = 1$, the product $\Gamma(1 - p) \sin(\pi p)$ in the denominator above is interpreted as the limiting value as $p \rightarrow 1$, which is π .

Proof Note that when X is strictly stable, $\delta^* = 0$. First assume $0 < p < \min(1, \alpha)$ and substitute Lemma 4 into this case of Theorem 1

$$\begin{aligned} EX_+^p &= \frac{\gamma^p \Gamma(p+1)}{\pi} \left[\sin(\pi p/2) \left(\frac{\Gamma(1 - p/\alpha)}{p} - \left((\cos \alpha \theta_0)^{-p/\alpha} \cos(-p\theta_0) - 1 \right) \frac{\Gamma(1 - p/\alpha)}{-p} \right) \right. \\ &\quad \left. - \cos(\pi p/2) (-\cos(\alpha \theta_0))^{-p/\alpha} \sin(-p\theta_0) \frac{\Gamma(1 - p/\alpha)}{-p} \right] \\ &= \frac{\gamma^p \Gamma(p+1) \Gamma(1 - p/\alpha)}{\pi p (\cos \alpha \theta_0)^{p/\alpha}} [\sin(\pi p/2) \cos(p\theta_0) + \cos(\pi p/2) \sin(p\theta_0)] \\ &= \frac{\gamma^p \Gamma(p+1) \Gamma(1 - p/\alpha)}{\pi p (\cos \alpha \theta_0)^{p/\alpha}} \sin(\pi p/2 + p\theta_0) \end{aligned}$$

Using the identity $\Gamma(p+1) = \pi p / (\Gamma(1-p) \sin p\pi)$ gives the result.

When $p = 1 < \alpha$, again using the appropriate part of Theorem 1 shows

$$\begin{aligned} EX_+ &= \gamma \left[0 + \frac{1}{\pi} \left(\Gamma(1 - 1/\alpha) - \left((\cos \alpha \theta_0)^{-1/\alpha} \cos(-\theta_0) - 1 \right) \frac{\Gamma(1 - 1/\alpha)}{-1} \right) \right] \\ &= \frac{\gamma \Gamma(1 - 1/\alpha)}{\pi} \left[\cos \alpha \theta_0 \right]^{-1/\alpha} \cos(\theta_0). \end{aligned}$$

When $1 < p < \alpha$, using Theorem 1 and $\delta^* = 0$,

$$\begin{aligned} EX_+^p &= \frac{\gamma^p \Gamma(p+1)}{\pi} \left[\sin(\pi p/2) \left(\frac{\Gamma(1 - p/\alpha)}{p} - \left((\cos \alpha \theta_0)^{-p/\alpha} \cos(-p\theta_0) - 1 \right) \frac{\Gamma(1 - p/\alpha)}{-p} \right) \right. \\ &\quad \left. + \cos(\pi p/2) \left(0 - \cos(\alpha \theta_0)^{-p/\alpha} \sin(-p\theta_0) \right) \frac{\Gamma(1 - p/\alpha)}{-p} \right], \end{aligned}$$

and the rest is like the first case. \square

The standard parameterization used above is discontinuous in the parameters near $\alpha = 1$, and it is not a scale-location family when $\alpha = 1$. To avoid this, a continuous parameterization that is a scale-location family can be used. We will say $X \sim \mathbf{S}(\alpha, \beta, \gamma, \delta; 0)$ if it has characteristic function

$$E \exp(iuX) = \begin{cases} \exp(-\gamma |u| [1 + i\beta(\tan \frac{\pi}{2})(\text{sign } u)(|\gamma u|^{1-\alpha} - 1)] + i\delta u) & \alpha \neq 1 \\ \exp(-\gamma |u| [1 + i\beta(2/\pi)(\text{sign } u) \log(\gamma |u|)] + i\delta u) & \alpha = 1. \end{cases}$$

A stable r. v. X can be expressed in both the 0-parameterization and the 1-parameterization, in which case the index α , the skewness β and the scale γ are the same. The only difference is in the location parameter: if X is simultaneously $\mathbf{S}(\alpha, \beta, \gamma, \delta_0; 0)$ and $\mathbf{S}(\alpha, \beta, \gamma, \delta_1; 1)$, then the shift parameters are related by

$$\delta_1 = \begin{cases} \delta_0 - \beta \gamma \tan \frac{\pi}{2} & \alpha \neq 1 \\ \delta_0 - (2/\pi) \beta \gamma \log \gamma & \alpha = 1. \end{cases}$$

Therefore, if $X \sim \mathbf{S}(\alpha, \beta, \gamma, \delta_0; 0)$,

$$EX_+^p = \begin{cases} m^p(\alpha, \beta, \gamma, \delta_0 - \beta \gamma \tan \frac{\pi}{2}) & \alpha \neq 1 \\ m^p(\alpha, \beta, \gamma, \delta_0 - (2/\pi) \beta \gamma \log \gamma) & \alpha = 1. \end{cases}$$

This quantity is continuous in all parameters.

For the above expressions for EX_+^p to be of practical use, one must be able to evaluate $g_d(\cdot|\alpha, \beta)$ and $\tilde{g}_d(\cdot|\alpha, \beta)$. When d is a nonnegative integer, Nolan (2017) gives Zolotarev type integral expressions for these functions. However, this is not helpful here, where negative, non-integer values of d are needed. We have written a short R program to numerically evaluate the defining integrals for $g_d(\cdot|\alpha, \beta)$ and $\tilde{g}_d(\cdot|\alpha, \beta)$. A single evaluation takes less than 0.0002 seconds on a modern desktop. This is faster than numerically evaluating $EX_+^p = \int_0^\infty x^p f(x|\alpha, \beta, \gamma, \delta) dx$, because the latter requires many numerical calculations of the density $f(x|\alpha, \beta, \gamma, \delta)$.

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